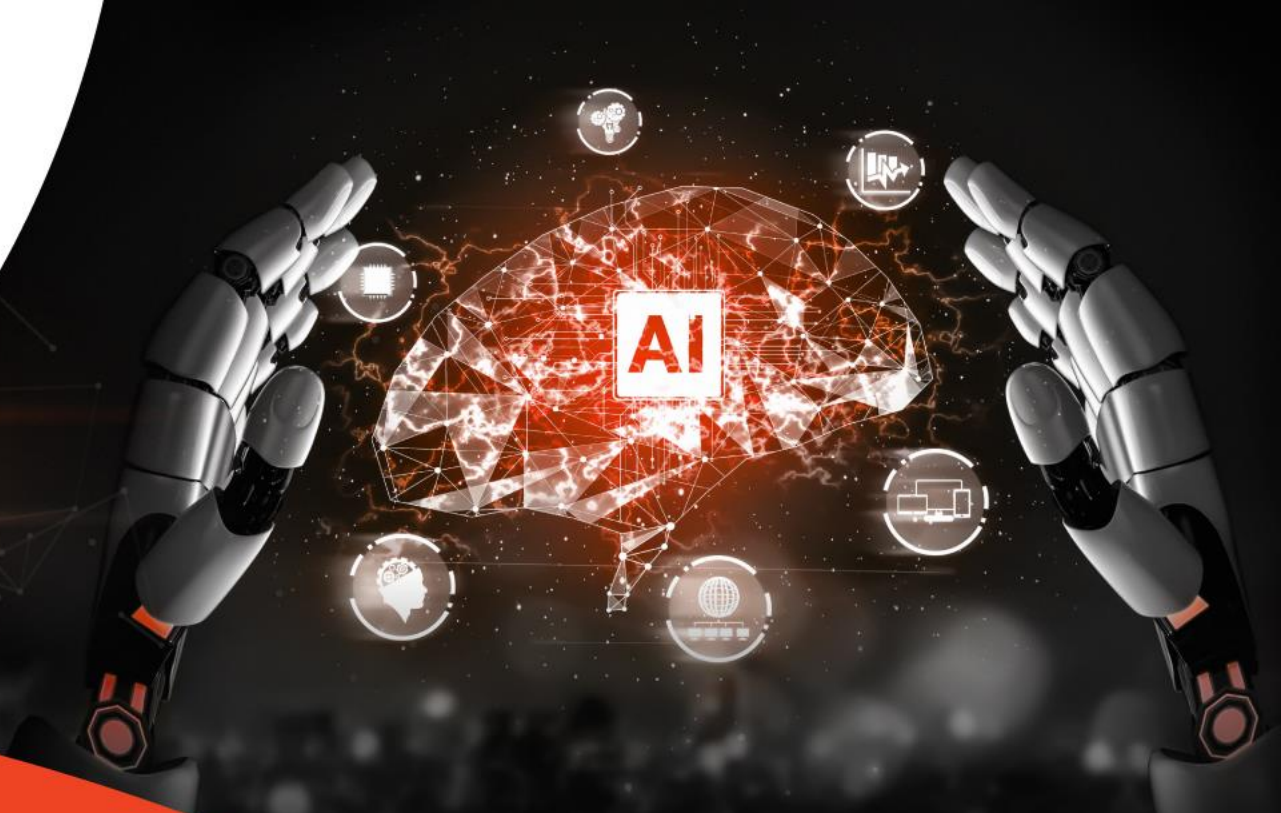


Agimus Winter School
11/12/2023 - 15/12/2023
Banyuls (France)



Thank you!

Nicolas Mansard
CNRS



Funded by the
European Union under
GA no 101070165.



Practical information

- Don't forget to give your key



- Leave tomorrow?
 - Leave anytime
 - No breakfast
 - (but dinner on Friday)



Agimus teachers



Florent Lamiroux
planning



Justin Carpentier
models



Mederic Fourmy
perception



Narcís Miguel
i Baños
architecture



Vladimir Petrik
perception



Guilhem Saurel
software



Wilson Jallet
constraints



Louis Montaut
collisions



Quentin Le Lidec
simulation

Assisted by Kateryna Zorina, Armand Jordana, Maximilien Naveau,
David Kovar, Martin Cifka, Ajay Sathya, Ludovic de Matteis

Keynote speakers



Timothy Bretl
Univ. Illinois



Ludovic Righetti
New York Univ.



Adrien Taylor
Inria Paris



Adrien Escande
Inria Grenoble

Administrative support

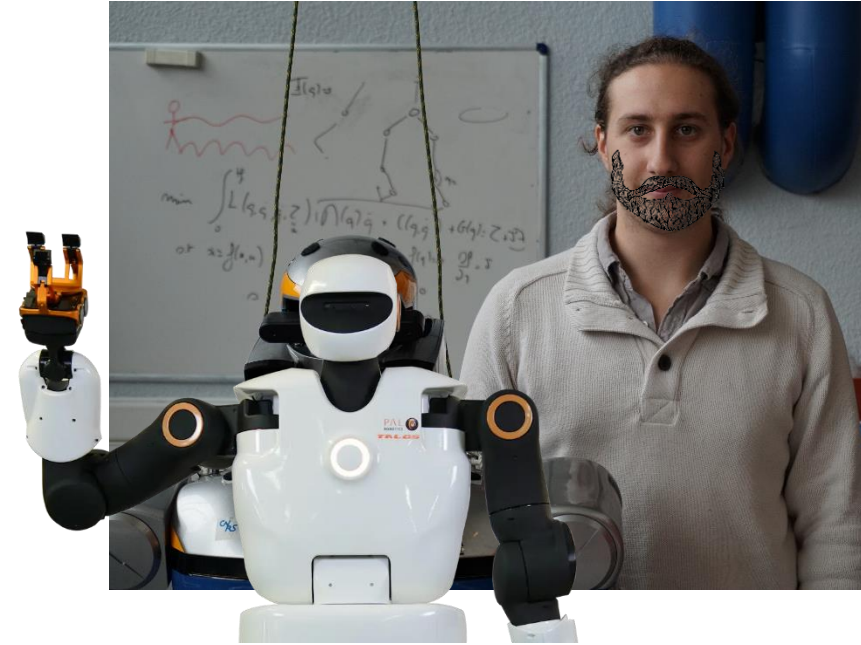
- LAAS administrative support
 - Christele Mouclier, Financial Manager of Agimus
- Observatoire Océanologique de Banyuls
 - Patricia Fuentes



Technical support

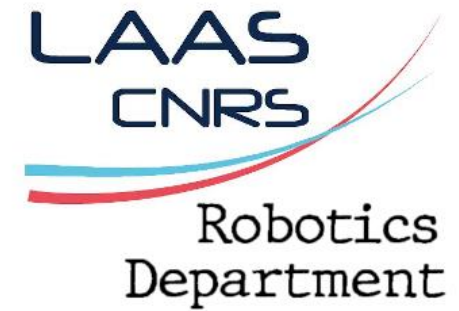


Guilhem Saurel
Research Engineer LAAS-CNRS



Maximilien Naveau
Research Engineer Toward

Funding agencies

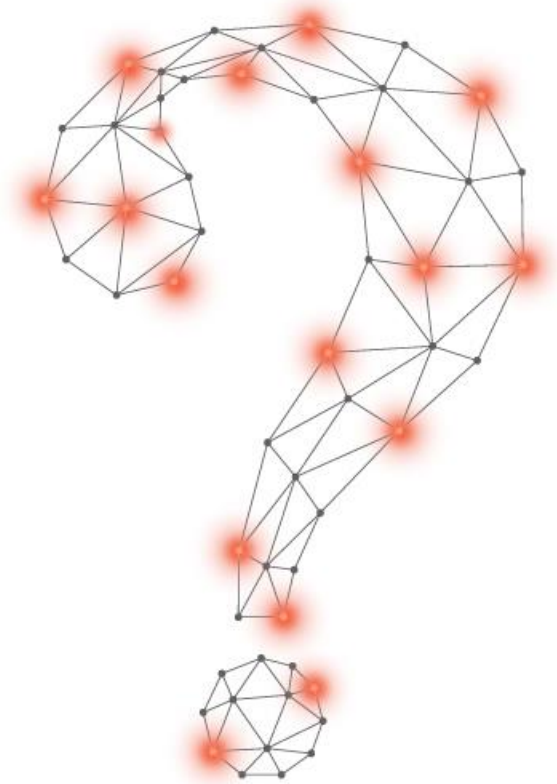


Materials

- Slides in the shared repository
- Repository with code is open source
- Talks will be (mostly) online on <https://peertube.laas.fr>
- Summary of all these information on <https://aws.sciencesconf.org>

- [matrix] is going to stay alive, ask questions
- Invite the teachers in your labs
- Come visit us, apply for post doc

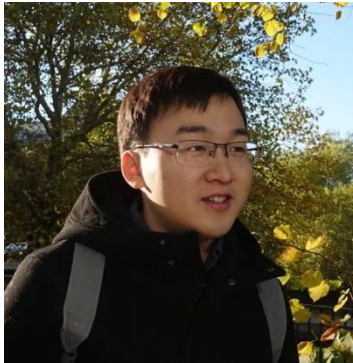
- We will send a participation certificate
 - I can sign specific paper if you need



Awarding the best posters

■ Panel

- Kateryna Zorina(CTU)
- Armand Jordana (INRIA/NYU)
- Ajay Sathya (INRIA)
- Quentin Le Lidec (INRIA)
- Louis Montaut (INRIA)
- Wilson Jallet (INRIA)



Jiayun Li

Technische Universität Darmstadt

*Learning Optimal Open-Loop
Robot Motion as Dynamic Systems
and Future Directions*

AWS Best Poster



Joaquim Ortiz-Haro

Technische Universität Berlin

iDb-A: Iterative Search and
Optimization for Optimal
Kinodynamic Motion Planning*

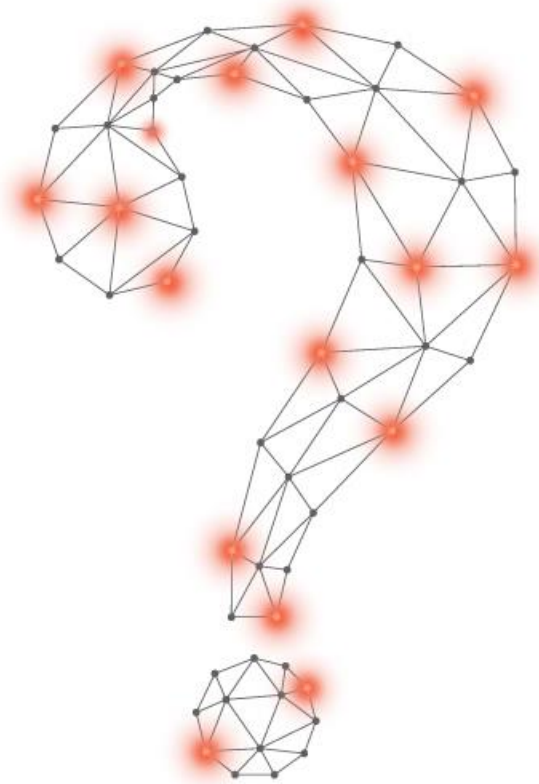


Khaled Wahba

Technische Universität Berlin

*Kinodynamic Motion Planning for
a Team of Multirotors Transporting
a Cable-Suspended Payload*

Questions and Answers



Contact Details

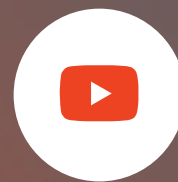
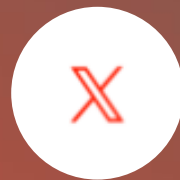
Nicolas Mansard

CNRS

nmansard@laas.fr



Thank you very much for your attention!



www.agimus-project.eu