

# A comparison of human skeleton extractors for real-time human-robot interaction

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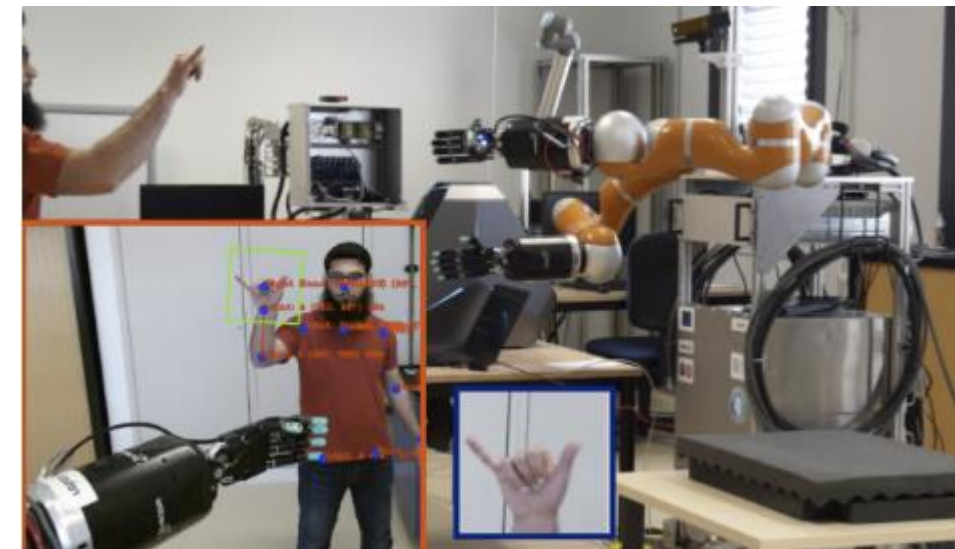
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## Motivation:

Safety insurance



Context understanding



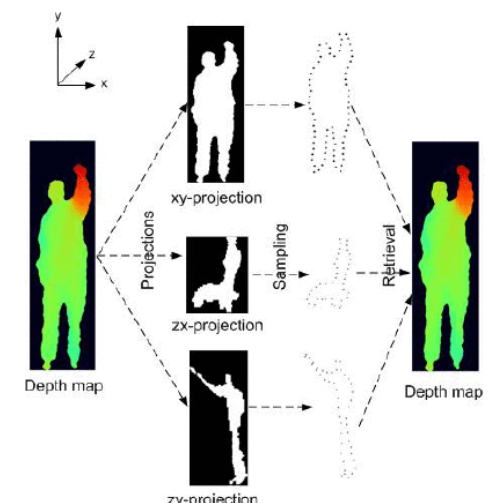
Ergonomic adaptation



## Multi-modal data for activity recognition:

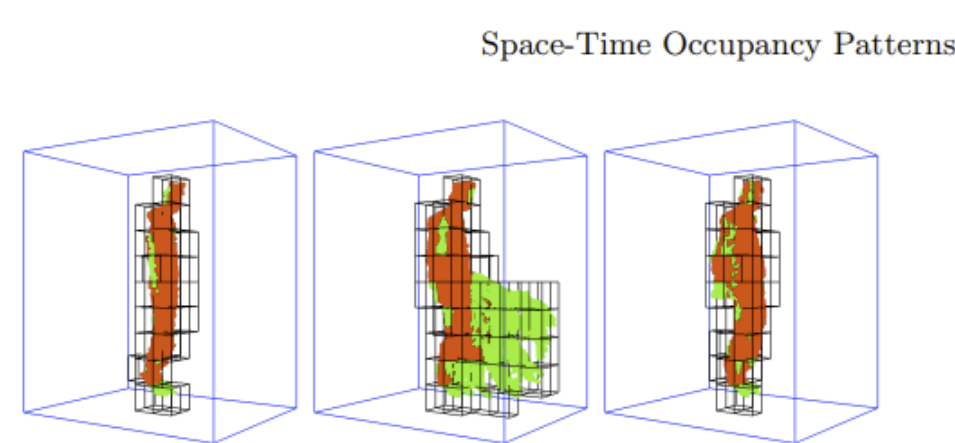
3D silhouette

- Limited for atomic actions recognition  
- Occlusion will degrade the extraction.



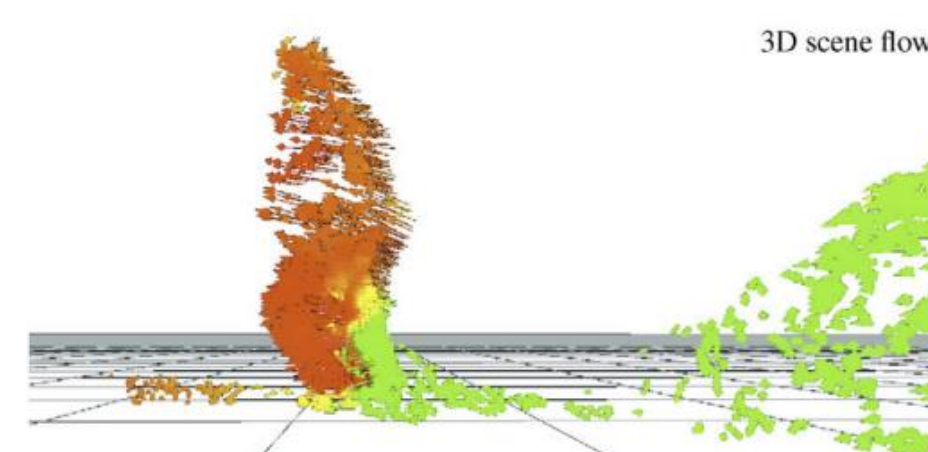
Space-time occupancy pattern

- Pattern can be sparse.  
- High computation cost



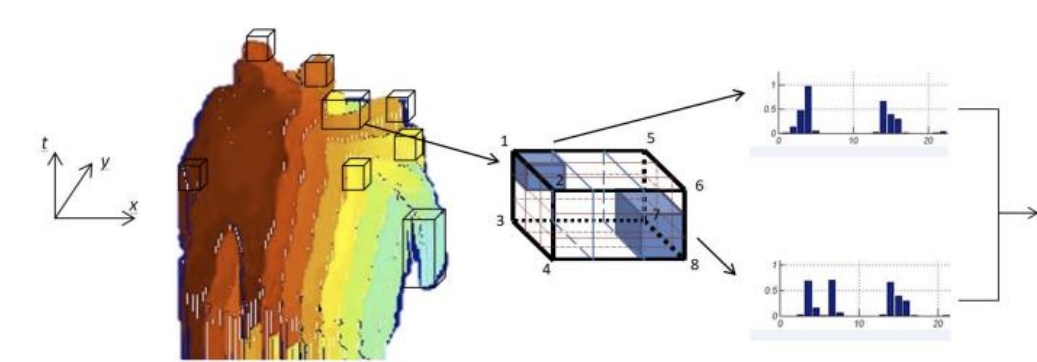
3D optical flow

- Computationally costly  
- Not suitable for real time application



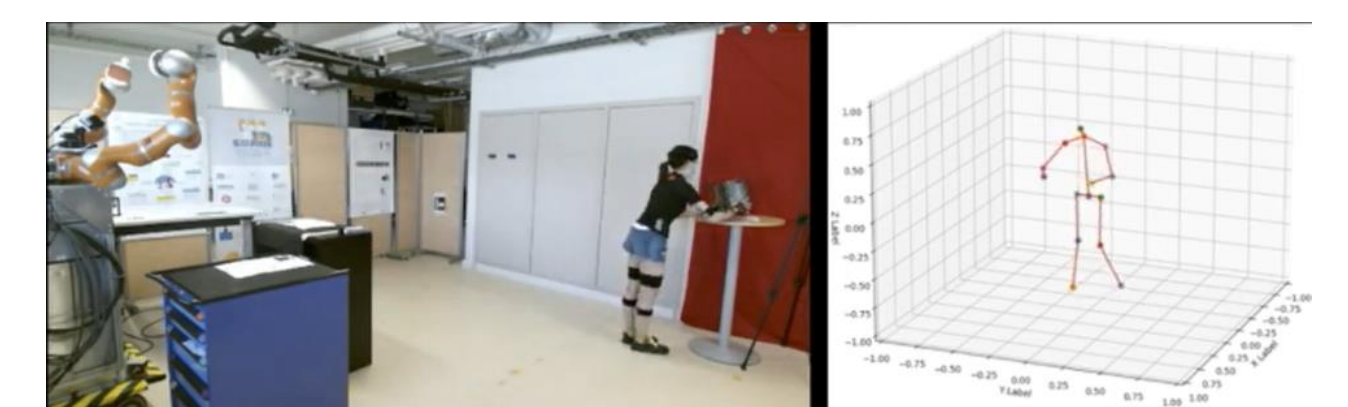
Local spatial temporal features

+ No need for segmentation or tracking  
- The feature is view-dependent and local.



Skeletal data

+ Invariant to the camera location, subject appearance and human body size  
+ Can be combined with biomechanical model  
- Current estimation algorithm is not perfect.



## Skeleton extraction frameworks comparison:

### General functionality:

| Skeleton extractors | Framework  | Output                          | Technique   | Specialty  |
|---------------------|------------|---------------------------------|---|--|
| Detectron2          | Pytorch    | 17 key-points                   | Segmentation on each key-point, one-step estimation                       | Segmentation   |
| MediaPipe           | Tensorflow | 33 key-points with 3d inference | Two-step estimation, region of interest detector + joint position tracker | Joint position tracking  |
| YOLOv7              | Pytorch    | 17 key-points                   | One-step estimation   | Occlusion does not influence detection   |
| ALPHA POSE          | Pytorch    | 17/26/136 key-points            | Two-step estimation   | Pose aware identity mechanism  |
| OpenPose            | Caffe      | 15/18/25/67/137 key-points      | Two-step estimation, Using part affinity fields                           | Direct C++ API is available<br>3D estimation is possible upon multiple synchronized camera views |

### Performance evaluation:

| Skeleton extractors | Identification | Multi-person detection | Foot keypoints | Hand keypoints | Facial keypoints     | Easy C++ interfacing | Robustness with respect to motion | GPU integration | Framerate |
|---------------------|----------------|------------------------|----------------|----------------|----------------------|----------------------|-----------------------------------|-----------------|-----------|
| Detectron2          | ×              | ✓                      | ×              | ×              | ears,eyes,nose       | ×                    | ✓                                 | ✓               | 3.57 fps  |
| Mediapipe           | ✓              | ×                      | ✓              | ✓              | ears,eyes,nose,mouth | ×                    | ×                                 | ✓ on Linux      | 17 fps    |
| YOLOv7              | ×              | ✓                      | ×              | ×              | ears,eyes,nose       | ×                    | ✓                                 | ✓               | 11.04 fps |
| Alphapose           | ✓              | ✓                      | ×              | ×              | ears,eyes,nose,mouth | ×                    | ✓                                 | ✓               | 9.74 fps  |
| Openpose            | ×              | ✓                      | ✓              | ✓              | ears,eyes,nose,mouth | ✓                    | ✓                                 | ✓               | 9.91 fps  |

## Future work:

- Quantitative comparison of 5 frameworks' outputs
- Using OpenPose library with human biomechanical model to estimate human skeleton on image inputs in real-time
- Human activity classification based on joint space information



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